## VF Series

AC INVERTERS vf-7e/Vf--7f/Vf-8XVFF-8z


## AC INVERTER LINE-UP



- Sensorless vector control
- Very low acoustic noise
- Multiple protection features
- Type approved under EC, LVD and EMC standards (EN Type)

| Single-phase 200V | 0.2 kW |  |  |
| :--- | :--- | :--- | :--- |
| Three-phase 200 V | 0.2 kW |  |  |
| Three-phase 400 V |  | 0.75 kW | 3.7 kW |

- Type approved under UL and CUL standards (UL Type)
Three-phase 200 V 0.2 kW 3.7kW
Three-phase $400 \mathrm{~V} \quad 0.75 \mathrm{~kW} \quad 3.7 \mathrm{~kW}$

IP20


## VF series inverters with enhanced, sophisticated functioning meet the world's toughest approvals, and fulfill the global market's demanding needs.

Standard line-up with the TÜV/UL/CUL-approved inverters


- Approved product range



Complying with TÜV and UL Standards-Designed for improved safety, operability and functionality

VF-7E
Series


## Safety

■ Product conforming to the EC Low Voltage Directive (TÜV-approved product)

- Conforms to DIN VDE 0160
$■$ Product conforming to the UL standard


## Accident prevention system

- Data lock function controlled by password.


## $\square$ Also conforms to the EMC Directive

- By combination use with EMI filter.

■ Programmable password for operational integrity
Electronic thermal overload

## Operability

- Improved monitoring functions
- Simple operation for frequency settings.
- The main display on the control panel can be altered between command frequency, output frequency and other settings.
- The four most recent faults are stored in the memory after a power failure to facilitate system diagnosis.


Indication of frequency, trip cause(s), etc.

- Frequency resolution

Digital setting: Min. 0.01 Hz
Analog setting: Min. 0.1 Hz

- Trip cause(s)

Instantaneous overcurrent (ground fault and high temperature), overcurrent, overvoltage, low voltage, auxiliary interlock, overload, operation error and auxiliary stop

Indication of Local/External control for operation signal and frequency signal, parameter number, etc.

## Functions

## Simple vector control

- Simple vector control ensures a high torque even at low speeds ( $150 \%$ torque at 1 Hz ).
- The output torque characteristics for general-purpose motors when operated by an inverter at variable speeds are shown below.


Auto tuning function (with slip compensation)

- This function automatically detects and controls the constant of a motor required for vector control and is applicable to three-phase squirrel-cage motors with 2,4 or 6 poles.


## Speed search function

- The inverter is activated without stopping the motor (on a free run) for a changeover from the commercial run to an inverter run or a return from sudden power failure.



## Improved tripless function

- This function automatically decreases the frequency when the output current reaches the overcurrent stall level during overload operation.
- When the load returns to normal, the function automatically returns the frequency to its original level and continues operation.
- The function prevents overcurrent trips in equipment such as kneading machines that are used for viscous materials.



## ■ Panel reset function

- After a trip, you can reset by pressing the stop button on the control panel, rather than through an external signal. (The function can be modified.)


## MODELS

| Applied motor output | UL Type |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 200V Three-Phase Series |  |  |  | 400 V Three-Phase Series |  |  |  |
|  | Catalogue.No. | Rated output (A) | Rated capacity (kVA) | $\begin{aligned} & \text { Mass } \\ & (\mathrm{kg}) \end{aligned}$ | Catalogue.No. | Rated output (A) | Rated capacity (kVA) | $\begin{aligned} & \text { Mass } \\ & (\mathrm{kg}) \end{aligned}$ |
| $\begin{aligned} & 0.2 \mathrm{~kW} \\ & (1 / 2 \mathrm{HP}) \\ & \hline \end{aligned}$ | BFV70022E | 2.3 | 0.9 | 1.2 | - | - | - | - |
| $\begin{aligned} & \text { O. } 4 \mathrm{~kW} \\ & (3 / 4 \mathrm{HP}) \\ & \hline \end{aligned}$ | BFV70042E | (2.5) | 1.2 | 1.2 | - | - | - |  |
| $\begin{aligned} & \text { O. } 5 \mathrm{kWW} \\ & \text { (iHP) } \end{aligned}$ | BFV70072E | (4.1) | 2.0 | 1.5 | BFV70074E | 2.1 | 1.7 | 2.5 |
| $\begin{aligned} & 1.5 \mathrm{KW} \\ & (2 \mathrm{HP}) \end{aligned}$ | BFV70152E | $(7)$ | 3.2 | 1.6 | BFV70154E | $\begin{gathered} 4^{4} \\ (3.8) \end{gathered}$ | 3.2 | 2.7 |
| 2. 2 kW (3P) | BFV70222E | (11) | 4.4 | 3.0 | BFV70224E | (5.4) | 4.8 | 2.9 |
| $\begin{aligned} & 3.7 \mathrm{~kW} \\ & (5 \mathrm{HP}) \end{aligned}$ | BFV70372E | $\begin{aligned} & 17.5 \\ & (16.5) \end{aligned}$ | 7.0 | 3.0 | BFV70374E | (8.7) | 7.5 | 3.1 |


| Applied motor output | EN Type |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 200 V Single-Phase Series |  |  |  | 200V Three-Phase Series |  |  |  | 400V Three-Phase Series |  |  |  |
|  | Catalogue.No. | Rated output (A) | $\begin{aligned} & \text { Rated } \\ & \text { Rutput } \\ & \text { capacity } \\ & \text { (kVA) } \end{aligned}$ | Mass (kg) | Catalogue.No. | Rated output (A) | $\begin{aligned} & \text { Rated } \\ & \text { Output } \\ & \text { capacity } \\ & \text { (kVA) } \end{aligned}$ | $\begin{aligned} & \text { Mass } \\ & (\mathrm{kg}) \end{aligned}$ | Catalogue.No. | Rated output (A) | $\begin{aligned} & \text { Rated } \\ & \text { output } \\ & \text { capacity } \\ & \text { (kVA) } \end{aligned}$ | $\begin{aligned} & \text { Mass } \\ & (\mathrm{kg}) \end{aligned}$ |
| $\begin{aligned} & 0.2 \mathrm{~kW} \\ & (1 / 2 \mathrm{HP}) \end{aligned}$ | BFV70022EBP | 2.0 | 0.8 | 1.4 | BFV70022EP | 2.0 | 0.8 | 1.4 | - | - | - | - |
| O. 3 kW $(3 / 4 \mathrm{HP}$ ) | BFV70042EBP | 2.8 | 1.2 | 1.4 | BFV70042EP | 2.8 | 1.2 | 1.4 | - | - | - | - |
| $\begin{aligned} & 0.75 \mathrm{~kW} \\ & (1 \mathrm{HP}) \end{aligned}$ | BFV70072EBP | 3.6 | 1.5 | 1.5 | BFV70072EP | 3.6 | 1.5 | 1.5 | BFV70074EP | 2.1 | 1.5 | 2.5 |
| (1.5kW | BFV70152EBP | 7.0 | 2.9 | 2.7 | BFV70152EP | 7.0 | 2.9 | 1.6 | BFV70154EP | 3.8 | 2.7 | 2.7 |
| ( 2.2 kW | BFV70222EBP | 9.1 | 3.8 | 3.0 | BFV70222EP | 9.1 | 3.8 | 3.0 | BFV70224EP | 5.4 | 3.9 | 2.9 |
| 3.7 kW $(5 \mathrm{HP})$ | - | - | - | - | BFV70372EP | 15.5 | 6.4 | 3.1 | BFV70374EP | 8.7 | 6.3 | 3.1 |

## STANDARD SPECIFICATIONS

The rated output current, rated output capacity, etc. of three phase 200 V and 400 V EN types are slightly different from those UL types.
The figures in parentheses are those when the carrier frequency is set at 2.5 kHz or more.

Models


200V Three-Phase Series
0.2 to 3.7 kW

3-phase, 200 to 230 V (240V)
$\square$ 0.2 to 2.2 kW 3-phase, 200 to 240 V 0.75 to 3.7 kW
$150 \%$ of rated output current for 1 minute
Three phase, 200 to $230 \mathrm{~V}\left(240 \mathrm{~V}\right.$ ), $50 / 60 \mathrm{~Hz} ~\left(\begin{array}{l|l|}\text { Single phase, } 200 \text { to } 240 \mathrm{~V}, 50 / 60 \mathrm{~Hz} & \text { Three phase, } 380 \text { to } 460 \mathrm{~V}(415 \mathrm{~V}), 50 / 60 \mathrm{~Hz} \\ \hline\end{array}\right.$ $\pm 10 \%$ of rated AC input voltage $\pm 5 \%$ of rated input frequency
Continuous operation at 165 V or more, or at less than 165 V for 15 ms .
COMMON SPECIFICATIONS

| Overvoltage category |  |  | II |
| :---: | :---: | :---: | :---: |
| Pollution degree |  |  | 2 |
|  | Output frequency range |  | 0 |
|  | Frequency display |  | D |
|  | Output frequency accuracy |  | $\pm$ |
|  | Frequency setting resolution |  | D |
| Inverter control |  |  |  |
| Carrier frequency |  |  |  |
|  | Start/Stop |  | S |
|  | Forward/Reverse |  | S |
|  | Jog operation |  | O |
|  | Stop select |  | S |
|  | Reset |  | S |
|  | Stop frequency |  | S |
|  | Instantaneous power failure restart |  | S |
| $\begin{aligned} & \text { 은 } \\ & \text { ర̀ర } \end{aligned}$ | Frequency setting signal |  | D |
|  | Voltage/frequency characteristics |  | S |
|  | 2nd voltage/frequency characteristics |  | O |
|  | 2nd torque boost level |  | O |
|  | Torque boost |  | O |
|  | Accel./Decel. time |  | 0 |
|  | Accel./Decel. characteristics |  |  |
|  | Accel./Decel. time 2, 3, and 4 |  | 0 |
|  | Multispeed frequency settings |  | U |
|  | Skip frequency setting |  | U |
|  | Upper frequency setting |  | S |
|  | Lower frequency setting |  | S |
|  | Bias and gain frequency settings |  | B |
|  | External fault trip |  | S |
| $\begin{array}{\|l\|} \hline \frac{1}{0} \text {. } \\ \text { Non } \\ \hline \end{array}$ | Braking torque | Regenerative braking | 2 |
|  |  | DC dynamic braking | W |
|  | Operation frequency signal |  | O- |
|  | Output signal |  | O |
|  |  |  |  |
| $\begin{aligned} & \text { त } \\ & \frac{0}{0} \\ & \frac{0}{0} \end{aligned}$ | Operating conditions |  | O |
|  | Fault trip buffers |  | D |
| $\begin{aligned} & \text { 든 } \\ & \text { 응 } \\ & \text { 은 } \end{aligned}$ | Current limit |  | C |
|  | Shut-off (stop) |  |  |
|  | Stall prevention |  | O |
|  | Ambient temperature and relative humidity |  |  |
|  | Storage and transport temperature, relative humidity |  | - |
|  | Vibration |  | 5 |
|  | Installation condition |  | A |

0.2 to 400 Hz

Digital display
$\pm 0.5 \%$ of selected maximum output frequency $\left(25 \pm 10^{\circ} \mathrm{C}\right)$ for analog setting
Digital setting; $0.01 \mathrm{~Hz}(0.1 \mathrm{~Hz}$ over 100 Hz$)$ Analog setting; $0.1 \mathrm{~Hz}(50 / 60 \mathrm{~Hz}$ by parameter setting)
High carrier frequency sinusoidal PWM control
(Select from V/F control method or simple vector control method)
Variable from 0.8 to 15 kHz
Select with operation panel buttons, 1 a contact signal (either 1a, 1b contact signal)
or wait time setting (0.1 to 100sec.)
Select with operation panel buttons, 1a contact signal (reverse operation prohibit setting possible)
Optional setting for 0.2 to 20 Hz
Optional Accel./Decel. time setting for 0.04 to 1600 seconds
Select from; ramp-to-stop or coast-to-stop
Select from; rest by power supply or by inputting stop signal. External reset setting is also possible.
Select from 0.2 to 60 Hz
Select from; function OFF, restart at OHz , or restart at the setting frequency
Digital setting; Operation panel
Analog setting; 0-5V DC, 0-10V DC, 4-20mA DC, $10 \mathrm{k} \Omega$ potentiometer
input impedance at $50 \mathrm{k} \Omega$ (0-5V DC) 20k $\Omega$ (0-10V DC), and approx. $350 \Omega$ (4-20mADC)
Select from; $50 \mathrm{~Hz}, 60 \mathrm{~Hz}$, optional base frequency setting for 45 Hz to 400 Hz ,
onstant torque, or square low torque pattern
Optional base frequency setting for 45 to 400 Hz
Optional setting for 0 to 40\%
Optional setting for 0 to $40 \%$
0.04 to 1600 sec . Individual accel. and decel. time setting

Linear/S-characteristics (selection switchover)
0.1 to 1600 sec. Individual accel. and decel. time setting Can be linked with multispeed setting.

Up to 8 preset frequency settings (programmable) Can be linked with accel. and decel. time setting.
Up to 3 place settings (skip frequency band setting from 1 to 10 Hz )
Setting for 0.2 to 400 Hz
Setting for 0.2 to 400 Hz
Bias: set for- 99.9 to $400 \mathrm{~Hz} \quad$ Gain: set for 0 to 400 Hz
Select from: auxiliary interlock fault or auxiliary stop (coast-to-stop)
20\% min. (0.2kW; 100\% min. 0.4kW; 80\% min.)
Working at less than setting stop frequency (braking torque and braking time settings) 0-5V DC
Open collector output (50V, 50mA max.) Run signal, arrival signal, frequency detection signal, overload alarm signal, reverse operation signal (selectable)
1c contact output (contact capacity at 250 V AC, resistance load at 0.5A) Fault alarm signal, run signal,
frequency detection signal, overload alarm signal, reverse operation signal (selectable)
Output frequency, setting frequency (F1) (A2) Line speed display (selection switchover)
Output current (AO), output voltage (A1), rotation direction
Display when protective functions are activated (last 4 faults are stored).
Current limit can be set from 1 to 200\% of rated output current
Instantaneous overcurrent, over temperature (SC), overcurrent (OC), low voltage (LU), overvoltage (OU),
auxiliary interlock (AU), overload/electronic thermal overload (OL), operation error (OP),
Overcurrent stall prevention, regenerative overvoltage stall prevention
$-10^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}\left(+14^{\circ} \mathrm{F}\right.$ to $\left.+122^{\circ} \mathrm{F}\right){ }^{* 1}$ (non-freezing), $90 \%$ RH max (non-condensing)
$-25^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}\left(-13^{\circ} \mathrm{F}\right.$ to $\left.+149^{\circ} \mathrm{F}\right), 95 \%$ RH max.
$5.9 \mathrm{~m} / \mathrm{s}^{2}$ (0.6G) max.
Altitude of 1000 m or less, indoors, free of corrosive gases and dust
P20 screen-protected type
$* 1-10^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}\left(+14^{\circ} \mathrm{F}\right.$ to $\left.+104^{\circ} \mathrm{F}\right)$ in case of EN types

## MODE DISPLAY (RUN/FAULT)

| Mode display | Run signal | Frequency signal | Main display (Examples) |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ei | Local (Operation panel) <br> Local (Operation panel) <br> External (Control terminal block | Local (Operation panel) <br> Extemal (Control terminal block) <br> Local (Operation panel) | Frequency display | Instantaneous overcurrent during acceleration or abnormal I heating of heat | Overcurrent during acceleration | $\begin{gathered} \text { Excessive } \\ \text { Internal DC } \\ \text { voltage } \\ \text { during } \\ \text { acceleration } \\ \text { (overvoltage) } \end{gathered}$ | Undevotage | $\underset{\substack{\text { Auxiliay } \\ \text { interiock }}}{ }$ | Overload | $\underset{\substack{\text { Operation } \\ \text { error }}}{ }$ | ${ }_{\substack{\text { Auxiliay } \\ \text { stop }}}$ |
| Es | Exteral (Contol termina block) | Exernal (Contro terminal block) | 50.00 | $55:$ | It: | 0121 | [1: | ALi | 012 | $0 \cdot$ | 15 |

## PARAMETER SETTINGS

| Parameter №. | Parameter name | Parameter object | Setting value or code |  |  |  |  |  |  |  | Factory setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 87 | 1st Accel Time | Sets acceleration time: 0.2 Hz to max. output frequency. | 0000: 40msec., 0.1~1600sec. |  |  |  |  |  |  |  | 005.0 |
| He | 1st Decel Time | Sets deceleration time: max output frequency to 0.2 Hz . | 0000: 40msec., 0.1~1600sec. |  |  |  |  |  |  |  | 005.0 |
| \% ${ }^{3}$ | Freq. Range | Sets V/F pattern. | 50 | 60 | FF | (50:50Hz, 60:60Hz, FF:FREE) |  |  |  |  | 60 |
| 5 | V/F (Volts-per-Hertz) Curve | Sets V/F curve. | 0 | 1 (0 | (0: Constant torque, 1: Reduced torque) |  |  |  |  |  | 0 |
| 5 | DC Boost Level | Sets torque boost level. | 0 ~ 40\% |  |  |  |  |  |  |  | 05 |
| 58 | Overload Function | Selects thermal overload functions. | 0 OFF | $1 \begin{gathered}\text { without output } \\ \text { Freq. derating }\end{gathered}$ |  | $2$ | with Freq. | output derating |  |  | 2 |
| 57 | Overload Current | Sets current value. | 0.1~100A |  |  |  |  |  |  |  | * |
| 5 | Local/Ext. Control | Specifies local or external control. | 0~6 |  |  |  |  |  |  |  | 0 |
| \% | Local/Ext. Freq. | Specifies local or external frequency control (Volts/Current). | Local | $\operatorname{VR}(10 \mathrm{k})$ |  | $\stackrel{2}{0 \sim 5 \mathrm{~V}}$ |  | $\stackrel{3}{0} 10 \mathrm{~V}$ |  |  | 0 |
| \% | Reverse Lockout | Specifies forward-only operation. | $\xrightarrow{\mathrm{O}} \underset{\text { Forward operation/Reverse operation }}{ }$ |  |  | Forward operation (No reverse operation) |  |  |  |  | 0 |
| 17 | Stop Mode Select | Specifies ramp-to-stop or coast-to-stop. | Ramp-to-stop |  | Coast-to-stop |  |  |  |  |  | 0 |
| \% | Stop Freq. | Sets stop frequency. | 0.2~60Hz |  |  |  |  |  |  |  | 00.50 |
| 13) | DC Brake Time | Sets DC dynamic brake time. | 000:OFF, 0.1~30sec. |  |  |  |  |  |  |  | 000 |
| 148 | DC Brake Level | Sets DC dynamic brake level. | 0~100 |  |  |  |  |  |  |  | 00 |
| 15 | Max. Freq. | Sets maximum output frequency. | $50 \sim 400 \mathrm{~Hz}$ |  |  |  |  |  |  |  | 60.00 |
| 15 | Base Freq. | Sets base frequency. | $45 \sim 400 \mathrm{~Hz}$ |  |  |  |  |  |  |  | 60.00 |
| 17 | Accel. Freq. Hold | Selects accel stall prevention. | $\begin{aligned} & \mathrm{O} \\ & \text { No } \end{aligned}$ |  | Available |  |  |  |  |  | 1 |
| [838 | Decel. Freq. Hold | Selects decel stall prevention. | $\begin{aligned} & \mathrm{O} \\ & \mathrm{No} \end{aligned}$ |  | Available |  |  |  |  |  | 1 |
| 18 | Preset Function Select | Selects multi-speed functions. | $\begin{gathered} 0 \\ \text { Multi-speed } \end{gathered}$ | d 1 <br> Accel/Decel  |  | Multi-speed linked to Accel/Decel |  |  |  |  | 0 |
| En | Multifunction Input Select | Selects functions for SW 1,2 and 3. | Values | 01 | 12 | 34 | 5 | 67 | 8 | 10 | 0 |
| $E$ ? | SW4 Function Select | Selects a function for SW4. | Second Characteristic 2 selected |  |  |  | $\begin{gathered} 1 \\ \text { Speed search } \end{gathered}$ |  |  |  | 0 |
| E® | Aux. Interlock | Specifies auxiliary interlock trip or auxiliary stop. | Auxiliary interlock |  |  |  | $\begin{aligned} & 1 \\ & \hline \text { Auxiliary stop } \end{aligned}$ |  |  |  | 0 |
| E3 | Output Terminal Select | Selects detection frequency functions. Selects output terminal functions. | $\begin{gathered} \mathrm{O} \\ \text { Run } \end{gathered}$ | $\begin{gathered} 1 \\ \text { Arrival } \end{gathered}$ | $\begin{array}{c\|} 2 \\ \text { Overload } \end{array}$ | $\begin{array}{\|c\|c} \text { dieuainay } \\ \text { defeciorion } \end{array}$ |  | $\begin{aligned} & \text { Revese } \\ & \hline \text { poperem } \end{aligned}$ |  |  | 0 |
| E-9 | Output RY Select | Selects output relay functions. | $\begin{gathered} 0 \\ \text { Run } \end{gathered}$ | $\begin{gathered} 1 \\ \text { Arrival } \end{gathered}$ | $\begin{gathered} 2 \\ \text { Overload } \end{gathered}$ |  |  | Reverse |  |  | 5 |
| EIS | $\begin{array}{\|l\|} \hline \text { Detect Freq. } \\ \text { (Output Terminal) } \\ \hline \end{array}$ | Sets detection frequency value. | 0000,0.2~400Hz |  |  |  |  |  |  |  | 00.50 |
| Eta | Detect Freq. (Output RY) | Sets detection frequency value. | 0000,0.2~400Hz |  |  |  |  |  |  |  | 00.50 |
| E7 | Jog Freq. | Sets jog frequency value. | 0.2~20Hz |  |  |  |  |  |  |  | 10.00 |
| E8 | Jog.Accel. Time | Sets acceleration time of jog operation. | 0000: 40msec., 0.1~1600sec. |  |  |  |  |  |  |  | 005.0 |
| 58 | Jog Decel. Time | Sets deceleration time of jog operation. | 0000: 40msec., 0.1~1600sec. |  |  |  |  |  |  |  | 005.0 |
| 278 | Preset Freq. 2 | Sets Preset Frequency 2. | 0000: OV stop, 0.2~400Hz |  |  |  |  |  |  |  | 20.00 |
| 31 | Preset Freq. 3 | Sets Preset Frequency 3. | 0000: OV stop, 0.2~400Hz |  |  |  |  |  |  |  | 30.00 |
| 클 | Preset Freq. 4 | Sets Preset Frequency 4. | 0000: OV stop, 0.2~400Hz |  |  |  |  |  |  |  | 40.00 |
| 33 | Preset Freq. 5 | Sets Preset Frequency 5. | 0000: OV stop, 0.2~400Hz |  |  |  |  |  |  |  | 15.00 |
| 50-4 | Preset Freq. 6 | Sets Preset Frequency 6. | 0000: OV stop, 0.2~400Hz |  |  |  |  |  |  |  | 25.00 |
| 53 | Preset Freq. 7 | Sets Preset Frequency 7. | 0000: OV stop, 0.2~400Hz |  |  |  |  |  |  |  | 35.00 |
| 345 | Preset Freq. 8 | Sets Preset Frequency 8. | 0000: OV stop, 0.2~400Hz |  |  |  |  |  |  |  | 45.00 |
| 37 | Accel.Time 2 | Sets Accel. Time 2. | 0.1~1600sec. |  |  |  |  |  |  |  | 005.0 |
| 548 | Decel.Time 2 | Sets Decel. Time 2. | 0.1~1600sec. |  |  |  |  |  |  |  | 005.0 |
| 38 | Accel.Time 3 | Sets Accel. Time 3. | 0.1~1600sec. |  |  |  |  |  |  |  | 005.0 |
| -47 | Decel.Time 3 | Sets Decel. Time 3. | 0.1~1600sec. |  |  |  |  |  |  |  | 005.0 |
| 48 | Accel.Time 4 | Sets Accel. Time 4. | 0.1~1600sec. |  |  |  |  |  |  |  | 005.0 |
| -18) | Decel.Time 4 | Sets Decel. Time 4. | 0.1~1600sec. |  |  |  |  |  |  |  | 005.0 |
| 43 | 2nd Base Freq. | Sets base frequency 2. | 45~400Hz |  |  |  |  |  |  |  | 60.00 |
| 1-4-4 | 2nd DC Boost Level | Sets boost level 2. | 0~40\% |  |  |  |  |  |  |  | 05 |
| 43 | Skip Freq. 1 | Sets Skip Frequency 1. | 0000: OFF, $0.2 \sim 400 \mathrm{~Hz}$ |  |  |  |  |  |  |  | 0000 |

PARAMETER SETTINGS

| Parameter №. | Parameter name | Parameter object | Setting value or code |  |  |  | Factory setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| -45 | Skip Freq. 2 | Sets Skip Frequency 2. | 0000: OFF, $0.2 \sim 400 \mathrm{~Hz}$ |  |  |  | 0000 |
| 47 | Skip Freq. 3 | Sets Skip Frequency 3. | 0000: OFF, 0.2~400Hz |  |  |  | 0000 |
| -48 | Skip Freq.Band Width | Sets skip frequency bands. | 0: OFF, 1~10Hz |  |  |  | 0 |
| 4 | Current Limit Function | Sets the current limit function. | 00:OFF, 0.1~9.9 |  |  |  | 00 |
| 57 | Power Loss Start Mode | Selects restart action when the power is turned on. | $\begin{gathered} 0 \\ \text { Run } \end{gathered}$ | $\begin{gathered} 1 \\ \text { Stop } \\ \hline \end{gathered}$ | $\begin{array}{\|c} \hline \text { 2 } \\ \hline \text { Ruer } \\ \text { wait timer } \\ \hline \end{array}$ | $\begin{gathered} 3 \\ \text { Stop } \\ \hline \end{gathered}$ | 1 |
| 51 | Ride-Thru Restart | Selects instantaneous power failure function. | $\begin{gathered} \mathrm{O} \\ \mathrm{OFF} \\ \hline \end{gathered}$ | $\begin{gathered} 1 \\ \text { ostrat } \\ \text { restart } \end{gathered}$ | $\begin{gathered} \text { Continued } \\ \text { Cestart } \end{gathered}$ |  | 0 |
| E8) | Wait Time | Sets waiting time for parameters 50 and 51. | 0.1~100 sec. |  |  |  | 000.1 |
| 53 | Accel./Decel. Pattern | Sets Accel/Decel patterns. |  | $\begin{gathered} 1 \\ \substack{\text { s.shaped } \\ \text { AccelDecel }} \\ \hline \end{gathered}$ |  |  | 0 |
| 54 | Lower Freq. Clamp | Sets lower frequency. | $0.2 \sim 400 \mathrm{~Hz}$ |  |  |  | 00.50 |
| 55 | Upper Freq. Clamp | Sets upper frequency. | $0.2 \sim 400 \mathrm{~Hz}$ |  |  |  | 400.0 |
| 58 | Bias/Gain Function Select | Selects enabling or disabling this function. | $\stackrel{\mathrm{O}}{\mathrm{OFF}}$ | $\mathrm{O}_{1}^{1}$ |  |  | 0 |
| 57 | Bias Freq. | Sets bias frequency. | -99.9~400Hz |  |  |  | 000.0 |
| 58 | Gain Freq. | Sets gain frequency. | 0000: OV stop, 0.2~400Hz |  |  |  | 60.00 |
| 58 | 0-5V Output Voltage compensation | Adjusts the 0~5V output signal. | 75~125\% |  |  |  | 100 |
| $5]$ | Monitor Select | Selects monitoring modes. | $\begin{gathered} \mathrm{O} \\ \text { Frequency } \\ \hline \end{gathered}$ | $\begin{gathered} 1 \\ \text { Frequency } \\ \hline \end{gathered}$ | $\begin{array}{\|c\|} \hline 2 \\ \text { Line speed } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 3 \\ \hline \text { Line speed } \\ \hline \end{array}$ | 0 |
| E | Line Speed Multiplier | Sets line speed multiplier. | 000.1~100 |  |  |  | 030.0 |
| ER | Max. Output Voltage | Sets maximum output voltage to motor rating. | 000:OFF, 1~500V |  |  |  | 000 |
| 53 | OCS Level | Sets overcurrent stall prevention level. | 1~200\% |  |  |  | 140 |
| E-4 | Carrier Freq. | Sets carrier frequency. | 0.8/1.1/1.6kHz, 2.5/5.0/7.5/10.0/12.5/15.0kHz |  |  |  | 0.8 |
| 55 | Vector Control Select | Sets control system. | V/F control Vector control |  |  |  | 0 |
| ES | Motor Capacity Set | Sets applicable motor capacity. | 0.2/0.4/0.7/1.5/2.2/3.7 |  |  |  | * |
| 57 | Motor Poles Select | Matches the number of applicable motor poles. | 2/4/6 |  |  |  | 4 |
| $E 8$ | Motor Constant Measurement Function | Selects function for constant motor measurement. | $\stackrel{\mathrm{O}}{\mathrm{O}}$ | $\begin{gathered} \text { voltcomp } \\ \text { measurument } \end{gathered}$ |  | $\begin{array}{\|c\|} \hline \begin{array}{c} \text { Recommended } \\ \text { constant } \end{array} \\ \hline \end{array}$ | 0 |
| 58 | Voltage Compensation Constant | Sets the voltage compensation constant. | 00.01~99.99 |  |  |  | Recommended value |
| 77 | Slip Compensation Frequency | Sets the slip conpensation frequency. | -5.00~05.00 |  |  |  | 03.00 |
| 71 | Password | Sets password for data input (prevents operational errors). | 000: OFF, 1~999 Mask code |  |  |  | 000 |
| 78 | Setting Data Clear | Clears factory settings. | 0/1/2 |  |  |  | 0 |
| 73 | Baud Rate | Sets communication speed. | 300/600/1200/2400/4800/9600 |  |  |  | 9600 |
| 74 | Stop Bit Length | Sets stop bit length. | 1/2 |  |  |  | 1 |
| 75 | Parity Check | Sets parity bit. | 0/1/2 |  |  |  | 0 |
| 75 | No. of Communication Retries | Sets the number of communication retries. | 0~10 |  |  |  | 0 |
| 77 | CR/LF Select Validity | Selects CR or LF. | 0/1/2/3 |  |  |  | 0 |

Note: Data can be read only when the power is on.
Parameters in $\square$ can be set during inverter operation.
*The same value as inverter's rating.

## FUNCTION SETTING PROCEDURE



Terminal Function Selection by Parameter No. 20

| Parameter | $\begin{gathered} \text { Control } \\ \text { terminal } \\ \text { No. } 14 \end{gathered}$ | $\begin{gathered} \text { Control } \\ \text { terninal } \\ \text { No. } 15 \\ \hline \end{gathered}$ | Control terminal No. 16 | Parameter | $\begin{gathered} \text { Control } \\ \text { terninal } \\ \text { No. } 44 \\ \hline \end{gathered}$ |  | Control terminal No. 16 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| No. 20 | SW1 | SW2 | SW3 | No. 20 | SW1 | SW2 | SW3 |
| 0 | Multispeed function | Multispeed function | Multi-speed function | 5 | Multispeed function | Auxiliarystopinput | Reset input |
| 1 |  |  | Reset input | 6 |  |  | Reset lockout |
| 2 |  |  | Resetlockout | 7 |  |  | Jog function |
| 3 |  |  | Jog function | 8 | Analog input changeover |  | Reset input |
| 4 |  |  | Auxiliary stop output | 9 |  |  | Reset lockout |
|  |  |  |  | 10 |  |  | Jog function |

## - Notes on setting parameters

1. While the inverter is in operation, only values for the numbers in the $\square$ of parameter settings can be modified.
2. No values can be modified unless the Lock indicator is off.
3. While the inverter is stopped, it cannot be operated unless the Lock indicator is ON .
4. If the function setting returns to the "Operation Prep. Complete" state during data modification while an external start signal is received, the error code OP" will be displayed, and the inverter will remain inoperative
5. The values set by pressing the Set button are stored in the memory even if the power is off.


## Safety

$\square$ Product conforming.to the EC Low Voltage Directive (TÜV-approved product)

- Conforms to DIN VDE O160

■ Product conforming to the UL standard
■ Accident prevention system

- Data lock function controlled by password


## ■ Also conforms to the EMC Directive

- By combination use with EMI filter

■ Programmable password for operational integrity
$\square$ Electronic thermal overload

## Operability

- Easy to operate by means of Digital Parameter Programming on operation panel.
- Enhanced monitoring features and space saving design.
- Super compact design with very powerful and extensive parameters.


## Functions

- Matsushita's unique PWM control for good low speed torque and control.
- Programmable 15.0 kHz carrier frequency, low acoustic noise.


## Device Features

## Extensive Frequency Range Selection:

Frequency range selectable for $50 / 60 \mathrm{~Hz}$ and from 50 to 400 Hz independent of maximum output frequency ( 50 to 400 Hz ). Constant torque and low torque modes can also be selected.

## $\square$ Powerful Acceleration/Deceleration:

Torque boost capability offers powerful acceleration at optimum V/F ratio. In addition, the stall prevention feature greatly reduces inverter trips during rapid acceleration or deceleration.

## Frequency Skip Feature:

Vibrations resulting from resonance with associated facilities are prevented by skipping resonant frequencies. Up to three frequencies can be skipped, and skip frequency span is user adjustable.

## $\square$ Max. Output Voltage Setting:

The inverter output voltage can be adjusted by AVR (Automatic Voltage Regulator).

## ■ Jog Operation:

Select either local or external jog operation, for which acceleration/deceleration time can be independently specified.

## $\square$ Smooth Operation at Low Frequencies:

Our unique PWM control method ensures smooth operation in the low frequency range with minimum torque ripple.

## Overload Function Protection:

Complete motor overload protection over a wide range of operating conditions by selection of device functions according to motor characteristics.

## - Ride-Through Restart Capability:

Restarts after power failures or surges can be programmed in different modes depending on load or system conditions. A wait time programming feature is also included.

## System Features

## Operation Status Feedback:

Provides run, arrival, frequency detection and fault alarm signals. The user can create commands for the next process step using those signals.

## $\square$ Acceleration/Deceleration linked with Multispeed Operation:

In addition to multispeed (eight speeds) and multiacceleration/deceleration rates (four rates), this device enables combination of those rates (four speeds) with link capability. Flexible speed/acceleration/deceleration combinations allow easy system design.

## ■Wide Choice of Speed Control:

Motor speed can be controlled with external analog signal, manual control or in two to eight steps with external switching signal.

## ■ DC Brake Range and Time Adjustment:

To ensure reliable stopping during deceleration, DC braking can be activated when output frequency is reduced below the specified stop frequency $(0.5$ to 60 Hz$)$. The DC brake application time can be adjusted from 0 to 120 seconds.

## ■ Master-Slave (Proportional) Operation:

The 0-5 V output signal and bias gain features allow proportional operations for up to five inverters. This makes transfer system construction easier.
$\square$ More practical and effective application by combination use with NAiS PLC.

MODELS

| Applied motor output | UL Type |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 200V Three-Phase Series |  |  |  | 400 V Three-Phase Series |  |  |  |
|  | Catalogue.No. | Rated output (A) *1 | Rated output capacity (KVA) | Mass (kg) | Catalogue.No. | Rated output (A) *1 | Rated output capacity (kVA) | $\begin{aligned} & \text { Mass } \\ & (\mathrm{kg}) \end{aligned}$ |
| $\begin{aligned} & 0.2 \mathrm{~kW} \\ & (1 / 2 \mathrm{HP}) \end{aligned}$ | BFV70022F | 2.0 | 0.8 | 1.4 | - | - | - | - |
| ( 3.4 kW (4HP) | BFV70042F | 2.8 | 1.1 | 1.4 | - | - | - | - |
| O.75kW | BFV70072F | 3.6 | 1.4 | 1.5 | BFV70074F | 2.1 | 1.7 | 2.5 |
| (1.5kW | BFV70152F | 7.0 | 2.8 | 1.6 | BFV70154F | 3.8 | 3.0 | 2.7 |
| (2.2kW | BFV70222F | 9.1 | 3.6 | 3.0 | BFV70224F | 5.4 | 4.3 | 2.9 |
| 3.7 kW $(5 \mathrm{HP})$ | BFV70372F | 15.5 | 6.2 | 3.1 | BFV70374F | 8.7 | 6.9 | 3.1 |


| Applied motor output | EN Type |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 200V Single-Phase Series |  |  |  | 400 V Three-Phase Series |  |  |  |
|  | Catalogue.No. | Rated output <br>  | $\begin{aligned} & \text { Rated } \\ & \text { output } \\ & \text { capocity } \\ & \text { (kVA) } \end{aligned}$ | $\begin{aligned} & \text { Mass } \\ & (\mathrm{kg}) \end{aligned}$ | Catalogue.No. | Rated output (A) *2 | $\begin{aligned} & \text { Rated } \\ & \text { output } \\ & \text { capacicity } \\ & \text { (kVA) } \end{aligned}$ | $\begin{aligned} & \text { Mass } \\ & (\mathrm{kg}) \end{aligned}$ |
| $\begin{aligned} & 0.2 \mathrm{~kW} \\ & (1 / 2 \mathrm{HP}) \\ & \hline \end{aligned}$ | BFV70022FBP | 2.0 | 0.8 | 1.4 | - | - | - | - |
| $\begin{aligned} & \hline 0.4 W \\ & (3 / 4 H P) \end{aligned}$ | BFV70042FBP | 2.8 | 1.2 | 1.4 | - | - | - | - |
| ( O ( 7 kPW ) | BFV70072FBP | 3.6 | 1.5 | 1.5 | BFV70074FP | 2.1 | 1.5 | 2.5 |
| $\begin{aligned} & 1.5 \mathrm{~kW} \\ & (2 \mathrm{HP}) \\ & \hline \end{aligned}$ | BFV70152FBP | 7.0 | 2.9 | 2.7 | BFV70154FP | 3.8 | 2.7 | 2.7 |
| $\begin{aligned} & 2.2 \mathrm{~kW} \\ & \text { (3P) } \end{aligned}$ | BFV70222FBP | 9.1 | 3.8 | 3.0 | BFV70224FP | 5.4 | 3.9 | 2.9 |
| 3.7 kW $(5 \mathrm{HP})$ | - | - | - | - | BFV70374FP | 8.7 | 6.3 | 3.1 |

## 1<Precautions>

When using the carrier frequency at 12.5 kHz or 15 kHz , the output current must be decreased to the following values. (The current does not need to be decreased for capacities other than those listed below.)

- 3-phase 200 V input series 0.75 kW
12.5 kHz : (rated output current) $\times 0.95(3.4 \mathrm{~A})$ 15 kHz : (rated output current) $\times 0.9$ (3.2A)
- 3-phase 200V input series 3.7 kW
12.5 kHz : (rated output current) $\times 0.94(14.5 \mathrm{~A})$ 15 kHz : (rated output current) $\times 0.87(13.5 \mathrm{~A})$
- 3-phase 400 V input series 3.7 kW
12.5 kHz : (rated output current) $\times 0.81(7.0 \mathrm{~A})$ $15 \mathrm{kHz} \quad$ : (rated output current) $\times 0.62(5.4 \mathrm{~A})$


## *2<Precautions>

When using the carrier frequency at 12.5 kHz or 15 kHz , the output current must be decreased to the following values. (The current does not need to be decreased for capacities other than those listed below.)

- Single-phase 200 V input series 0.75 kW 12.5 kHz : (rated output current) $\times 0.95(3.4 \mathrm{~A})$ 15 kHz : (rated output current) $\times 0.9$ (3.2A)
- 3-phase 400V input series 3.7 kW
12.5 kHz : (rated output current) $\times 0.81$ (7.0A) $5 \mathrm{kHz} \quad:($ rated output current) $\times 0.62(5.4 \mathrm{~A})$

STANDARD SPECIFICATIONS

Models

|  | Rated output voltage |
| :---: | :---: |
|  | Overload capacity |
|  | Number of phases, voltage, frequency |
|  | Voltage variations |
|  | Frequency variations |
|  | Instantaneous voltage drop resistance |

0.2 to 3.7 kW

3-phase, 200 to 230 V
_
0.2 to 2.2 kW

3-phase, 200 to 240 V
e
$150 \%$ of rated output current for 1 minute

400V Three-Phase Series
0.75 to 3.7 kW

3-phase, 380 to 460 V (415V)
Three phase, 200 to $230 \mathrm{~V} ; 50 / 60 \mathrm{~Hz} \quad$ Single phase, 200 to $240 \mathrm{~V} ; 50 / 60 \mathrm{~Hz} \quad$ Three phase, 380 to $460 \mathrm{~V}(415 \mathrm{~V}) ; 50 / 60 \mathrm{~Hz}$ $\pm 10 \%$ of rated AC input voltage
$\pm 5 \%$ of rated input frequency
Continuous operation at 165 V or more, or at less than 165 V for 15 ms .

Continuous operation at 330 V or more, or at less than 330 V for 15 ms .
The figures in parentheses are those of EN types.

## COMMON SPECIFICATIONS

| Overvoltage category |  |  | II |
| :---: | :---: | :---: | :---: |
| Pollution degree |  |  | 2 |
|  | Output frequency range |  | 0.5 to 400 Hz |
|  | Frequency display |  | Digital display |
|  | Output frequency accuracy |  | $\pm 0.5 \%$ of selected maximum output frequency ( $25 \pm 10^{\circ} \mathrm{C}$ ) for analog setting |
|  | Frequency setting resolution |  | Digital setting; $0.1 \mathrm{~Hz}(1 \mathrm{~Hz}$ over 100 Hz ) Analog setting; $0.1 \mathrm{~Hz}(50 / 60 \mathrm{~Hz}$ by parameter setting) |
| Inverter control |  |  | High carrier frequency sinusoidal PWM control |
| Carrier frequency |  |  | Variable from 0.8 to 15 kHz |
| $\begin{aligned} & \text { 으 } \\ & \text { O} \\ & \text { ©0 } \\ & \hline 0 \end{aligned}$ | Start/Stop |  | Select with operation panel buttons, 1a contact signal (either 1a, 1b contact signal) or wait time setting ( 0.1 to 100 sec .) |
|  | Forward/Reverse |  | Select with operation panel buttons, 1a contact signal (reverse operation prohibit setting possible) |
|  | Jog operation |  | Optional setting for 0.5 to 400 Hz <br> Optional Accel./Decel. time setting for 0.04 to 999 seconds |
|  | Stop select |  | Select from; ramp-to-stop or coast-to-stop |
|  | Reset |  | Select from; rest by power supply or by inputting stop signal. External reset setting is also possible. |
|  | Stop frequency |  | Select from 0.5 to 60 Hz |
|  | Instantaneous power failure restart |  | Select from; function OFF, restart at O Hz, or restart at the setting frequency |
| $\begin{aligned} & \overline{2} \\ & \text { 응 } \end{aligned}$ | Frequency setting signal |  | Digital setting; Operation panel <br> Analog setting; 0-5V DC, 0-10V DC, 4-20mA DC, $10 \mathrm{k} \Omega$ potentiometer, input impedance at 200k $\Omega$ (0-5V DC, 0-10V DC), and approx. $200 \Omega$ (4-20mA DC) |
|  | Voltage/frequency characteristics |  | Select from; $50 \mathrm{~Hz}, 60 \mathrm{~Hz}$, optional base frequency setting for 45 Hz to 400 Hz , constant torque, or square low torque pattern |
|  | 2nd voltage/frequency characteristics |  | Optional base frequency setting for 45 to 400 Hz |
|  | 2nd torque boost level |  | Optional setting for 0 to 40\% |
|  | Torque boost |  | Optional setting for 0 to 40\% |
|  | Accel./Decel. time |  | 0.04 to 999sec. Individual accel. and decel. time setting |
|  | Accel./Decel. time 2, 3, and 4 |  | 0.1 to 999sec. Individual accel, and decel. time setting Can be linked with multispeed setting. |
|  | Multispeed frequency settings |  | Up to 8 preset frequency settings (programmable) Can be linked accel. and decel. time setting. |
|  | Skip frequency setting |  | Up to 3 place settings (skip frequency band setting from 1 to 10 Hz ) |
|  | Upper frequency setting |  | Setting for 0.5 to 400 Hz |
|  | Lower frequency setting |  | Setting for 0.5 to 400 Hz |
|  | Bias and gain frequency settings |  | Bias: set for-99 to 400 Hz Gain: set for 0 to 400 Hz |
|  | External fault trip |  | Select from: auxiliary interlock fault or auxiliary stop (coast-to-stop) |
|  | Braking torque | Regenerative braking | 20\% min. (0.2kW; 100\% min. 0.4kW; 80\% min.) |
|  |  | DC dynamic braking | Working at less than setting stop frequency (braking torque and braking time settings) |
|  | Operation frequency signal |  | 0-5V DC |
|  | Output signal |  | Open collector output (50V, 50mA max.) Run signal, arrival signal, frequency detection signal, overload alarm signal, reverse operation signal (selectable) |
|  |  |  | 1c contact output (contact capacity at 250 V AC, resistance load at 0.5 A ) Fault alarm signal, run signal, frequency detection signal, overload alarm signal, reverse operation signal (selectable) |
| $\begin{aligned} & \frac{\pi}{0} \\ & \frac{0}{0} \\ & \hline \end{aligned}$ | Operating conditions |  | Output frequency, line speed display (selection switchover) Output current, rotation direction |
|  | Fault trip buffers |  | Display when protective functions are activated (last 4 faults are stored). |
|  | Current limit |  | Current limit can be set from 1 to 200\% of rated output current |
|  | Shut-off (stop) |  | Instantaneous overcurrent, over temperature (SC), overcurrent (OC), low voltage (LU), overvoltage (OU), auxiliary interlock (AU), overload/electronic thermal overload (OL), operation error (OP), |
|  | Stall prev | ntion | Overcurrent stall prevention, regenerative overvoltage stall prevention |
|  | Ambient temperature and relative humidity |  | $-10^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}\left(+14^{\circ} \mathrm{F}\right.$ to $\left.+122^{\circ} \mathrm{F}\right) * 1$ (non-freezing), $90 \% \mathrm{RH}$ max (non-condensing) |
|  | Storage and transport temperature, relative humidity |  | $-25^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}\left(-13^{\circ} \mathrm{F}\right.$ to $\left.+149^{\circ} \mathrm{F}\right), 95 \%$ RH max. |
|  | Vibration |  | $5.9 \mathrm{~m} / \mathrm{s}^{2}$ (0.6G) max. |
|  | Installation condition |  | Altitude of 1000m or less |
|  | Enclosure |  | IP20 screen-protected type |

## MODE DISPLAY(RUN/FAULT)

| Main display (Examples) |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Frequency display | Instantaneous overcurrent during acceleration or abnormal heating of heat | Overcurrent during acceleration | $\begin{gathered} \text { Excessive } \\ \text { internal DC } \\ \text { voltage } \\ \text { during } \\ \text { acceleration } \\ \text { (overvoltage) } \end{gathered}$ | Underoltage | Auxiary | Overoad | $\underset{\substack{\text { Operation } \\ \text { eror }}}{\text { a }}$ | $\underset{\substack{\text { Auxiliary } \\ \text { siop }}}{ }$ |
| 50.0 | 551 | Di: | D2: | 1, | 9 Fi | 012 | $0 \cdot$ | AS |

Note: When the sudden power failure function is selected, "LU" is stored in the trip cause memory and does not send an alarm signal.
PARAMETER SETTINGS


PARAMETER SETTINGS

| Parameter No. | Parameter name | Parameter object | Sefting value or code |  |  |  | Factory setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Fo-45 | 2nd DC Boost Level | Sets boost level 2. | 0~40\% |  |  |  | 05 |
| F-17 | Skip Freq. 1 | Sets Skip Frequency 1. | 000: OFF, $0.5 \sim 400 \mathrm{~Hz}$ |  |  |  | 000 |
| Fr-4 | Skip Freq. 2 | Sets Skip Frequency 2. | 000: OFF, $0.5 \sim 400 \mathrm{~Hz}$ |  |  |  | 000 |
| Fr-4 | Skip Freq. 3 | Sets Skip Frequency 3. | 000: OFF, $0.5 \sim 400 \mathrm{~Hz}$ |  |  |  | 000 |
| F-5 | Skip Freq.Band Width | Sets skip frequency bands. | 0 : OFF, 1~10Hz |  |  |  | 0 |
| F5 | Current Limit Function | Sets the current limit function. | 00:OFF, 0.1~9.9 |  |  |  | 00 |
| F58] | Power Loss Start Mode | Selects restart action when the power is turned on. | $\begin{gathered} \mathrm{O} \\ \text { Run } \end{gathered}$ | $\begin{gathered} 1 \\ \text { Stop } \end{gathered}$ | $\begin{gathered} 2 \\ \begin{array}{c} \text { Rutter } \\ \text { Ralit time } \end{array} \end{gathered}$ | $\begin{gathered} 3 \\ \text { Stop } \end{gathered}$ | 1 |
| F53] | Ride-Thru Restart | Selects instantaneous power failure function. | $\begin{gathered} \mathrm{O} \\ \mathrm{OFF} \\ \hline \end{gathered}$ | $\begin{gathered} 1 \\ \text { ostar } \\ \text { restar } \end{gathered}$ | $\begin{aligned} & \text { Continued } \\ & \text { restar } \end{aligned}$ |  | 0 |
| F-54 | Wait Time | Sets waiting time for parameters 52 and 53. | $0.1 \sim 100 \mathrm{sec}$. |  |  |  | 00.1 |
| F53 | Lower Freq. Clamp | Sets lower frequency. | $0.5 \sim 400 \mathrm{~Hz}$ |  |  |  | 00.5 |
| P-58 | Upper Freq. Clamp | Sets upper frequency. | $0.5 \sim 400 \mathrm{~Hz}$ |  |  |  | 400 |
| F57 | Bias/Gain Function Select | Selects enabling or disabling this function. | $\begin{gathered} \mathrm{O} \\ \text { OFF } \end{gathered}$ | $\mathrm{O}^{1}$ |  |  | 0 |
| F58 | Bias Freq. | Sets bias frequency. | -99~400Hz |  |  |  | 00.0 |
| F58 | Gain Freq. | Sets gain frequency. | 000: OV stop, $0.5 \sim 400 \mathrm{~Hz}$ |  |  |  | 60.0 |
| F6\% | 0-5V Output Voltage compensation | Adjusts the 0~5V output signal. | 75~125\% |  |  |  | 100 |
| FFi | Monitor Select | Selects monitoring modes. | $\begin{array}{\|c\|} \hline \mathrm{O} \\ \text { Frequency } \\ \hline \end{array}$ | $\begin{gathered} 1 \\ \text { Line speed } \\ \hline \end{gathered}$ |  |  | 0 |
| F6, | Line Speed Multiplier | Sets line speed multiplier. | 0.1~100 |  |  |  | 03.0 |
| F63 | Max. Output Voltage | Sets maximum output voltage to motor rating. | 0:OFF, 1~500V |  |  |  | 000 |
| FF-4 | OCS Level | Sets overcurrent stall prevention level. | 1~200\% |  |  |  | 140 |
| P6, | Carrier Freq. | Sets carrier frequency. | 0.8/1.1/1.6kHz, 2.5/5.0/7.5/10.0/12.5/15.0kHz |  |  |  | 0.8 |
| F68 | Password | Sets password for data input (prevents operational errors). | 0: OFF, 1~999 Mask code |  |  |  | 000 |
| F\%7 | Setting Data Clear | Clears factory settings. | 0/1 |  |  |  | 0 |
| FF\% | Fault Display 1 | Displays the history of faults 1 | Most recent |  |  |  |  |
| F5\% | Fault Display 2 | Displays the history of faults 2 | Second most recent |  |  |  |  |
| P7 | Fault Display 3 | Displays the history of faults 3 | Third most recent |  |  |  |  |
| F7\% | Fault Display 4 | Displays the history of faults 4 | Fourth most recent |  |  |  |  |

Note: Data can be read only when the power is on.
Parameters in $\square$ can be set during inverter operation.

* The same current value as the rated current of the inverter.


## FUNCTION SETTING PROCEDURE



[^0]Super reliable, powerful and quiet operation inverters


## Safety

Accident prevention system

- Data lock function controlled by password


## ■ Programmable password for

 operational integrity
## ■ Electronic thermal overload

## - ※The followings are for VF-8X only.

- Product conforming to the EC Low Voltage Directive (TÜV-approved product)
- Conforms to DIN VDE 0160


## ■ Product conforming to the UL standard $\square$ Also conforms to the EMC Directive <br> - By combination use with EMI filter

## Operability

- Easy to operate by means of Digital Parameter Programming on operation panel.
- Enhanced monitoring features and space saving design
- Super compact design with very powerful and extensive parameters.


## Functions

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## Frequency Skip Feature:

Vibrations resulting from resonance with associated facilities are prevented by skipping resonant frequencies. Up to three frequencies can be skipped, and skip frequency span is user adjustable.

## $\square$ Max. Output Voltage Setting:

The inverter output voltage can be adjusted by AVR (Automatic Voltage Regulator).

## ■ Jog Operation:

Select either local or external jog operation, for which acceleration/deceleration time can be independently specified.

## Smooth Operation at Low Frequencies:

Our unique PWM control method ensures smooth operation in the low frequency range with minimum torque ripple.

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Complete motor overload protection over a wide range of operating conditions by selection of device functions according to motor characteristics.

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Provides run, arrival, frequency detection and fault alarm signals. The user can create commands for the next process step using those signals.

## $\square$ Acceleration/Deceleration linked with Multispeed Operation:

In addition to multispeed (eight speeds) and multiacceleration/deceleration rates (four rates), this device enables combination of those rates (four speeds) with link capability. Flexible speed/acceleration/deceleration combinations allow easy system design.

## Wide Choice of Speed Control:

Motor speed can be controlled with external analog signal, manual control or in two to eight steps with external switching signal.

## D DC Brake Range and Time Adjustment:

To ensure reliable stopping during deceleration, DC braking can be activated when output frequency is reduced below the specified stop frequency ( 0.5 to 60 Hz ). The DC brake application time can be adjusted from 0 to 30 seconds.

## ■ Master-Slave (Proportional) Operation:

The 0-5 V output signal and bias gain features allow proportional operations for up to five inverters. This makes transfer system construction easier.
$\square$ More practical and effective application by combination use with NAiS PLC.

MODELS

| Applied motor output | VF-8X Series |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | UL Type |  |  |  |  |  |  |  | EN Type |  |  |  |
|  | 200 V Three-Phase Series |  |  |  | 400 V Three-Phase Series |  |  |  | 400 V Three-Phase Series |  |  |  |
|  | Catalogue.No. | $\begin{aligned} & \text { Rated } \\ & \text { Cutput } \\ & \text { cut } \\ & \text { (A) } \end{aligned}$ | $\begin{aligned} & \text { Rated } \\ & \text { outtut } \\ & \text { ckVA) } \end{aligned}$ | Mass (kg) | Catalogue.No. | $\begin{aligned} & \text { Rated } \\ & \text { outut } \\ & \text { cutrut } \\ & \text { (A) } 1 \text { t } \end{aligned}$ | $\begin{aligned} & \text { Rated } \\ & \text { outbut } \\ & \text { (kVA) } \end{aligned}$ | Mass (kg) | Catalogue.No. | $\begin{aligned} & \text { Rated } \\ & \text { cutput } \\ & \text { cutp } \\ & (A) \star 1 \end{aligned}$ | $\begin{aligned} & \text { Rated } \\ & \text { output } \\ & \text { ckock } \end{aligned}$ | Mass (kg) |
| (5,5kW | BFV80552X | 22.0 | 8.8 | 4.0 | BFV80554X | 12.0 | 9.6 | 4.0 | BFV80554XP | 12.0 | 8.6 | 4.0 |
|  | BFV80752X | 33.0 | 13.1 | 10.0 | BFV80754X | 17.0 | 13.5 | 4.2 | BFV80754XP | 17.0 | 12.2 | 9.5 |
| (115HP) | BFV81102X | 45.0 | 17.9 | 13.0 | BFV81104X | 22.0 | 17.5 | 13.0 | BFV81104XP | 22.0 | 15.8 | 13.0 |
| $\left(\begin{array}{l}15 \mathrm{~kW} \\ (20 \mathrm{HP}) \\ \hline\end{array}\right.$ | BFV81502X | 61.0 | 24.3 | 13.0 | BFV81504X | 31.0 | 24.7 | 13.0 | BFV81504XP | 31.0 | 22.3 | 13.0 |
| (25HP) | BFV81902X | 75.0 | 29.9 | 20.0 | BFV81904X | 38.0 | 30.3 | 20.0 | BFV81904XP | 38.0 | 27.3 | 20.0 |
| (30kW) | BFV82202X | 87.0 | 34.7 | 20.0 | BFV82204X | 43.0 | 34.3 | 20.0 | BFV82204XP | 43.0 | 30.9 | 20.0 |
| (30kW) | BFV83002X | 117.0 | 46.6 | 30.0 | BFV83004X | 61.0 | 48.6 | 30.0 | BFV83004XP | 61.0 | 43.8 | 30.0 |
| (50HP) | BFV83702X | 140.0 | 55.8 | 31.0 | BFV83704X | 70.0 | 55.8 | 31.0 | BFV83704XP | 70.0 | 50.3 | 31.0 |


| Applied motor output | VF-8Z Series |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 400V Three-Phase Series |  |  |  |
|  | Catalogue.No. | Rated output curtont (A) (A) | $\begin{aligned} & \text { Rated } \\ & \text { output } \\ & \text { catoacity } \\ & \text { (kVA) } \end{aligned}$ | Mass (kg) |
| (5.5kW | BFV80554Z | 12.0 | 9.6 | 4.0 |
| ( (10HP) $^{\text {SkW }}$ | BFV80754Z | 17.0 | 13.5 | 4.2 |
| (115W) | BFV81104Z | 22.0 | 17.5 | 10.0 |
|  | BFV81504Z | 31.0 | 24.7 | 10.0 |
| (25kW) | BFV81904Z | 38.0 | 30.3 | 13.0 |
| (23kW) | BFV82204Z | 43.0 | 34.3 | 13.0 |
| 30 kW $(40 \mathrm{HP})$ | BFV83004Z | 61.0 | 48.6 | 20.0 |
| ( 50 HP ) | BFV83704Z | 70.0 | 55.8 | 24.0 |

*1 Note) The rated output current is for a carrie frequency of 10 kHz or less.
when using at 12.5 kHz or 15 kHz , decrease the rated current to the following values and use. -12.5 kHz : $($ rated current) $\times 0.9$

- 15.0 kHz : (rated current) $\times 0.8$
*2 Note) The rated output current is for a carrie frequency of 10 kHz or less. when using at 12.5 kHz or 15 kHz , decrease the rated current to the following values and use 1) $5.5 \sim 22 \mathrm{~kW}$
$\cdot 12.5 \mathrm{kHz}$ : $($ rated current $) \times 0.9$

2) $30,37 \mathrm{~kW}$ : (rated current) $\times 0.8$
$\cdot 15.0 \mathrm{kHz}$ : $($ rated current $) \times 0.7$

## STANDARD SPECIFICATIONS

| Models |  | 200V Three-Phase Series | 400V Three-Phase Series |
| :---: | :---: | :---: | :---: |
| Applied motor output |  | 5.5 to 37 kW | 5.5 to 37 kW |
|  | Rated output voltage | 3-phase, 200 to 230V | 3-phase, 380 to 460V (415V) |
|  | Overload capacity | $150 \%$ of rated output current for 1 minute |  |
|  | Number of phases, voltage, frequency | Three phase, 200 to $230 \mathrm{~V} ; 50 / 60 \mathrm{~Hz}$ | Three phase, 380 to 460 V (415V); 50/60Hz |
|  | Voltage variations | $\pm 10 \%$ of rated AC input voltage |  |
|  | Frequency variations | $\pm 5 \%$ of rated input frequency |  |
|  | Instantaneous voltage drop resistance | Continuous operation at 165 V or more, or at less than 165 V for 15 ms . | Continuous operation at 330V or more, or at less than 330 V for 15 ms . |

COMMON SPECIFICATIONS

| Overvoltage category |  |  | ㅍ(Not for VF-8Z) |
| :---: | :---: | :---: | :---: |
| Pollution degree |  |  | 2 (Not for VF-8Z) |
|  | Output frequency range |  | 0.2 to 400 Hz |
|  | Frequency display |  | Digital display |
|  | Output frequency accuracy |  | $\pm 0.5 \%$ of selected maximum output frequency ( $25 \pm 10^{\circ} \mathrm{C}$ ) for analog setting |
|  | Frequency setting resolution |  | Digital setting; $0.01 \mathrm{~Hz}(0.1 \mathrm{~Hz}$ over 100 Hz$) \quad$ Analog setting; $0.1 \mathrm{~Hz}(50 / 60 \mathrm{~Hz}$ by parameter setting) |
| Inverter control |  |  | High carrier frequency sinusoidal PWM control |
| Carrier frequency |  |  | Variable from 0.8 to 15 kHz (When using at 12.5 kHz or 15 kHzz , decrease the rated current) |
|  | Start/Stop |  | Select with operation panel buttons, 1a contact signal (either 1a, 1b contact signal) or wait time setting ( 0.1 to 100 sec .) |
|  | Forward/Reverse |  | Select with operation panel buttons, 1a contact signal (reverse operation prohibit setting possible) |
|  | Jog operation |  | Optional setting for 0.2 to 20 Hz <br> Optional Accel./Decel. time setting for 0.04 to 1600 seconds |
|  | Stop select |  | Select from; ramp-to-stop or coast-to-stop |
|  | Reset |  | Select from; reset by power supply or by inputting stop signal. External reset setting is also possible. |
|  | Stop frequency |  | Select from 0.2 to 60Hz |
|  | Instantaneous power failure restart |  | Select from; function OFF, restart at O Hz, or restart at the setting frequency |
| 은 | Frequency setting signal |  | Digital setting; Operation panel <br> Analog setting; 0-5V DC, $0-10 \mathrm{~V}$ DC, $4-20 \mathrm{~mA} \mathrm{DC}, 10 \mathrm{k} \Omega$ potentiometer, <br> input impedance at $50 \mathrm{k} \Omega$ (0-5V DC) $20 \mathrm{k} \Omega$ ( $0-10 \mathrm{~V}$ DC), and approx. $350 \Omega$ (4-20mA DC) |
|  | Voltage/frequency characteristics |  | Select from; $50 \mathrm{~Hz}, 60 \mathrm{~Hz}$, optional base frequency setting for 45 Hz to 400 Hz , constant torque, or square low torque pattern |
|  | 2nd voltage/frequency characteristics |  | Optional base frequency setting for 45 to 400 Hz |
|  | 2nd torque boost level |  | Optional setting for 0 to 40\% |
|  | Torque boost |  | Optional setting for 0 to 40\% |
|  | Accel./Decel. time |  | 0.04 to 1600 sec . Individual accel. and decel. time setting |
|  | Accel./Decel. characteristics |  | Linear/S-character characteristics (selection switchover) |
|  | Accel./Decel. time 2, 3, and 4 |  | 0.1 to 1600sec. Individual accel. and decel. time setting Can be linked with multispeed setting. |
|  | Multispeed frequency settings |  | Up to 8 preset frequency settings (programmable) Can be linked accel. and decel. time setting. |
|  | Skip frequency setting |  | Up to 3 place settings (skip frequency band setting for 1 to 10 Hz ) |
|  | Upper frequency setting |  | Setting for 0.2 to 400 Hz |
|  | Lower frequency setting |  | Setting for 0.2 to 400 Hz |
|  | Bias and gain frequency settings |  | Bias: set for-99.9 to 400Hz Gain: set for 0 to 400 Hz |
|  | External fault trip |  | Select from: auxiliary interlock fault or auxiliary stop (coast-to-stop) |
|  | Braking torque | Regenerative braking | 20\% min. |
|  |  | DC dynamic braking | Working at less than setting stop frequency (braking torque and braking time settings) |
|  | Operation frequency signal |  | 0-5V DC |
|  | Output signal |  | Open collector output (50V, 50mA max.) Run signal, arrival signal, frequency detection signal, overload alarm signal, reverse operation signal (seléctable) |
|  |  |  | 1 c contact output (contact capacity at 250 V AC, resistance load at 0.5 A ) Fault alarm signal, run signal, frequency detection signal, overload alarm signal, reverse operation signal (selectable) |
|  | Operating conditions |  | Output frequency, setting frequency (F1) (F2) Line speed display (selection switchover) Output current (AO), output voltage (A1), rotation direction |
|  | Fault trip | uffers | Display when protective functions are activated (last 4 faults are stored). |
|  | Current limit |  | Current limit can be set from 1 to 200\% of rated output current |
|  | Shut-off (stop) |  | Instantaneous overcurrent, over temperature (SC), overcurrent (OC), low voltage (LU), overvoltage (OU), auxiliary interlock (AU), overload/electronic thermal overload (OL), operation error (OP), |
|  | Stall prevention |  | Overcurrent stall prevention, regenerative overvoltage stall prevention |
|  | Ambient temperature and relative humidity |  | $-10^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}\left(+14^{\circ} \mathrm{F}\right.$ to $\left.+122^{\circ} \mathrm{F}\right){ }^{* 1}$ (non-freezing), $90 \% \mathrm{RH}$ max (non-condensing) |
|  | Storage and transport temperature, relative humidity |  | $-25^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}\left(-13^{\circ} \mathrm{F}\right.$ to $\left.+149^{\circ} \mathrm{F}\right), 95 \% \mathrm{RH}$ max. |
|  | Vibration |  | $5.9 \mathrm{~m} / \mathrm{s}^{2}$ (0.6G) max. |
|  | Installatio | condition | Altitude of 1000m or less |
| Enclosure |  |  | IP20 screen-protected type |

$-10^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}$ in case of the followings.
UL type(200V $5.5 \mathrm{~kW}, 400 \mathrm{~V} 5.5 \mathrm{~kW} \cdot 7.5 \mathrm{~kW})$

## MODE DISPLAY(RUN/FAULT)

| Mode display | Run signal | Frequency signal | Main display (Examples) |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| EL EF $E L$ | Local (Operation nanel) <br> Local (Operaion nanel) <br> Exienal (Control terminal block | Local (Operation panel) <br> Extenal (Control teminina block) <br> Local (Operation panel) <br> Externa (Control teminina block) | Frequency display |  | Overcurrent during acceleration accelat | $\begin{aligned} & \text { Excessive } \\ & \text { internal DC } \\ & \text { voltage } \\ & \text { during } \\ & \text { acceleration } \\ & \text { (overvoltage) } \end{aligned}$ | Undervoltage | Auxiary interlock | Overload | $\begin{aligned} & \text { Operation } \\ & \text { error } \end{aligned}$ | $\begin{gathered} \text { Auxiliary } \\ \text { stop } \end{gathered}$ |
|  |  |  | 5000 | 51 | DE: | Di: | 1.1) | Pii | 01 | $0 \cdot \mathrm{~F}$ | 95 |

Note: When the sudden power failure function is selected, "LU" is stored in the trip cause memory and does not send an alarm signal.

## PARAMETER SETTINGS



PARAMETER SETTINGS

| Parameter No. | Parameter name | Parameter object | Sefting value or code |  |  |  | Factory setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| -45 | Skip Freq. 2 | Sets Skip Frequency 2. | 0000: OFF, 0.2~400Hz |  |  |  | 0000 |
| 47 | Skip Freq. 3 | Sets Skip Frequency 3. | 0000: OFF, 0.2~400Hz |  |  |  | 0000 |
| -48 | Skip Freq.Band Width | Sets skip frequency bands. | 0 : OFF, 1~10Hz |  |  |  | 0 |
| -48) | Current Limit Function | Sets the current limit function. | 00:OFF, 0.1~9.9 |  |  |  | 00 |
| 57 | Power Loss Start Mode | Selects restart action when the power is turned on. | $\begin{gathered} \mathrm{O} \\ \text { Run } \end{gathered}$ | $\begin{gathered} 1 \\ \text { Stop } \\ \hline \end{gathered}$ |  | $\begin{gathered} 3 \\ \text { Stop } \\ \hline \end{gathered}$ | 1 |
| 51 | Ride-Thru Restart | Selects instantaneous power failure function. | $\begin{gathered} 0 \\ \text { OFF } \end{gathered}$ | $\begin{gathered} 1 \\ \text { restart } \\ \text { resta } \end{gathered}$ | $\begin{array}{\|c}  \\ \begin{array}{c} \text { tinule } \\ \text { Contuned } \\ \text { restart } \end{array} \\ \hline \end{array}$ |  | 0 |
| 58 | Wait Time | Sets waiting time for parameters 50 and 51. | 0.1~100 sec. |  |  |  | 000.1 |
| 53 | Accel./Decel. Pattern | Sets Accel/Decel patterns. | $\substack{\text { Linear } \\ \text { Accellocel }}$ | $\underset{\substack{\text { S-s.saped } \\ \text { AccelDecel }}}{\substack{\text { and }}}$ |  |  | 0 |
| 5-4 | Lower Freq. Clamp | Sets lower frequency. | $0.2 \sim 400 \mathrm{~Hz}$ |  |  |  | 00.50 |
| 53 | Upper Freq. Clamp | Sets upper frequency. | $0.2 \sim 400 \mathrm{~Hz}$ |  |  |  | 400.0 |
| 58 | Bias/Gain Function Select | Selects enabling or disabling this function. | $\stackrel{\mathrm{O}}{\mathrm{OFF}}$ | $\mathrm{O}^{1}$ |  |  | 0 |
| 57 | Bias Freq. | Sets bias frequency. | -99.9~400Hz |  |  |  | 000.0 |
| 58 | Gain Freq. | Sets gain frequency. | 0000: OV stop, 0.2~400Hz |  |  |  | 60.00 |
| 58 | 0-5V Output Voltage compensation | Adjusts the 0~5V output signal. | 75~125\% |  |  |  | 100 |
| ET | Monitor Select | Selects monitoring modes. | $\begin{gathered} \mathrm{O} \\ \text { Frequency } \\ \hline \end{gathered}$ | $\begin{gathered} 1 \\ \text { Frequency } \end{gathered}$ | $\begin{array}{\|c\|} \hline 2 \\ \hline \text { Line speed } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 3 \\ \text { Line speed } \\ \hline \end{array}$ | 0 |
| 51 | Line Speed Multiplier | Sets line speed multiplier. | 000.1~100 |  |  |  | 030.0 |
| ERI | Max. Output Voltage | Sets maximum output voltage to motor rating. | 000:OFF, 1~500V |  |  |  | 000 |
| 53 | OCS Level | Sets overcurrent stall prevention level. | 1~200\% |  |  |  | 140 |
| E4 | Carrier Freq. | Sets carrier frequency. | 0.8/1.1/1.6kHz, 2.5/5.0/7.5/10.0/12.5/15.0kHz |  |  |  | 0.8 |
| 53 | For manufacturer use only. | - | - |  |  |  | - |
| 58 | For manufacturer use only. | - | - |  |  |  | - |
| 57 | For manufacturer use only. | - | - |  |  |  | - |
| 58 | For manufacturer use only. | - | - |  |  |  | - |
| 58 | For manufacturer use only. | - | - |  |  |  | - |
| 77 | For manufacturer use only. | - | - |  |  |  | - |
| 71 | Password | Sets password for data input (prevents operational errors). | 000: OFF, 1~999 Mask code |  |  |  | 000 |
| 78 | Setting Data Clear | Clears factory settings. | 0/1/2 |  |  |  | 0 |
| 73 | Baud Rate | Sets communication speed. | 300/600/1200/2400/4800/9600 |  |  |  | 9600 |
| 748 | Stop Bit Length | Sets stop bit length. | 1/2 |  |  |  | 1 |
| 75 | Parity Check | Sets parity bit. | 0/1/2 |  |  |  | 0 |
| 75 | No. of Communication Retries | Sets the number of communication retries. | 0~10 |  |  |  | 0 |
| 77 | CR/LF Select Validity | Selects CR or LF. | 0/1/2/3 |  |  |  | 0 |

Note: Data can be read only when the power is on.
Parameters in $\square$ can be set during inverter operation.
*The same value as inverter's rating.
**5.5~15kW: 005.0, 19~37kW: 015.0

## FUNCTION SETTING PROCEDURE

 See parameter No.71. (Parameter No. modified) (Parameter No. modified)



Terminal Function Selection by Parameter No. 20

## - Notes on setting parameters

1. While the inverter is in operation, only values for the numbers in the $\square$ of parameter settings can be modified.
2. No values can be modified unless the Lock indicator is off
3. While the inverter is stopped, it cannot be operated unless the Lock indicator is ON .
4. If the function setting returns to the "Operation Prep. Complete" state during data modification while an external start signal is received, the error code "OP" will be displayed, and the inverter will remain inoperative.
5. The values set by pressing the Set button are stored in the memory even if the power is off.

| Parameter | $\begin{gathered} \text { Control } \\ \text { terninal } \\ \text { No. } 14 \\ \hline \end{gathered}$ | $\begin{gathered} \text { Control } \\ \text { terminal } \\ \text { No.15 } \\ \hline \end{gathered}$ | Control terminal No. 16 |
| :---: | :---: | :---: | :---: |
| No. 20 | SW1 | SW2 | SW3 |
| 0 | Multispeed function | Multispeed function | Multi-speed function |
| 1 |  |  | Reset input |
| 2 |  |  | Resetlockout |
| 3 |  |  | Jog function |
| 4 |  |  | Auxiliary stop output |


| Parameter | $\begin{aligned} & \text { Control } \\ & \text { terninal } \\ & \text { No. } \end{aligned}$ | $\begin{aligned} & \text { Confrol } \\ & \text { tern } \\ & \text { No. } \end{aligned}$ | Control terminal No. 16 |
| :---: | :---: | :---: | :---: |
| No. 20 | SW1 | SW2 | SW3 |
| 5 | Multispeed function | $\begin{aligned} & \text { Auxiliary } \\ & \text { stop } \\ & \text { input } \end{aligned}$ | Reset input |
| 6 |  |  | Reset lockout |
| 7 |  |  | Jog function |
| 8 | $\begin{gathered} \text { Analog } \\ \text { input } \\ \text { changeover } \end{gathered}$ |  | Reset input |
| 9 |  |  | Reset lockout |
| 10 |  |  | Jog function |

DIMENSIONS Unit:mm
<Figure No. Table>
※The models which are more than 1.5 kW are with fans.

| VF-7E |  | 0.2kW | 0.4 kW | 0.75 kW | 1.5kW | 2.2 kW | 3.7 kW |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Three-phase 200V | UL Type | Fig. 1 | Fig. 1 | Fig. 2 | Fig. 3 | Fig. 4 | Fig. 4 |
|  | EN Type | Fig. 2 | Fig. 2 | Fig. 2 | Fig. 3 | Fig. 4 | Fig. 4 |
| Single-phase 200V | EN Type | Fig. 2 | Fig. 2 | Fig. 2 | Fig. 4 | Fig. 4 | - |
| Three-phase 400V | UL/EN Type | - | - | Fig. 4 | Fig. 4 | Fig. 4 | Fig. 4 |
| VF-7F |  | 0.2kW | 0.4 kW | 0.75 kW | 1.5 kW | 2.2 kW | 3.7 kW |
| Three-phase 200V | UL Type | Fig. 2 | Fig. 2 | Fig. 2 | Fig. 3 | Fig. 4 | Fig. 4 |
| Single-phase 200V | EN Type | Fig. 2 | Fig. 2 | Fig. 2 | Fig. 4 | Fig. 4 | - |
| Three-phase 400V | UL/EN Type | - | - | Fig. 4 | Fig. 4 | Fig. 4 | Fig. 4 |
| VF-8X |  | 5.5 kW | 7.5kW | 11 kW | 15kW | 19/22kW | 30/37kW |
| Three-phase 200V | UL Type | Fig.A | Fig.B | Fig.B | Fig.D-2 | Fig.D-3 | Fig.D-4 |
| Three-phase 400V | UL Type | Fig.A | Fig.A | Fig.D-2 | Fig.D-2 | Fig.D-3 | Fig.D-4 |
|  | EN Type | Fig.A | Fig.D-1 | Fig.D-2 | Fig.D-2 | Fig.D-3 | Fig.D-4 |
| VF-8Z |  | 5.5 kW | 7.5kW | 11 kW | 15kW | 19/22kW | 30/37kW |
| Three-phase 400V | - | Fig.A | Fig.A | Fig.C | Fig.C | Fig.D-2 | Fig.E |



## WIRING DIAGRAM

## VF-7E VF-8X VF-8Z



## VF-7F



## - Control Circuit Wiring



Note:When setting the frequency with the 4 to 20 mA signal,short circuit terminal Nos. 2 and 10




## - For three phase 400 V

| Filter rated current | Inverter capacity | Product number | Dimensions |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | W1 L | L L | 1 H | D |
| 30A | $5.5,7.5 \mathrm{~kW}$ | BFV938X07514 |  | 1002 | 21018 | 80 |  |
| 40A | 11,15kW | BFV938X15014 | 147 | 11225 | 25022 | 201 | 40 |
| 60A | 19,22kW | BFV938X22014 |  | 11232 | 32029 | 9014 |  |

## - Standard specifications

| Power source | Max. 460V AC |
| :--- | :---: |
| Frequency | $50 / 60 \mathrm{~Hz}$ |
| Overload endurance | $150 \%$ of rated current for 1 minute |
| Leakage current | Max. 35mA |
| Ambient temperature | $-10^{\circ} \mathrm{C}$ to $40^{\circ} \mathrm{C}$ (no freezing) |
| humidity | Max. $90 \%$ RH (no condensation) |
| Storage and <br> transporting temp. <br> and humidity | $-10^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (no freezing) |
| Applicable category | Group 1, class A (EN55011:1991) |

## - Dimensions



OPTION
Panel holder Product

[^1]$\qquad$

## Matsushita Electric Works, Ltd.

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■ Telephone: Japan (81) Osaka (06) 908-1050
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[^0]:    - Notes on setting parameters

    1. While the inverter is in operation, only values for the numbers in the $\square$ of parameter settings can be modified.
    2. The values set by pressing the set button are stored in the memory even if the power is off.
[^1]:    Please contact

